

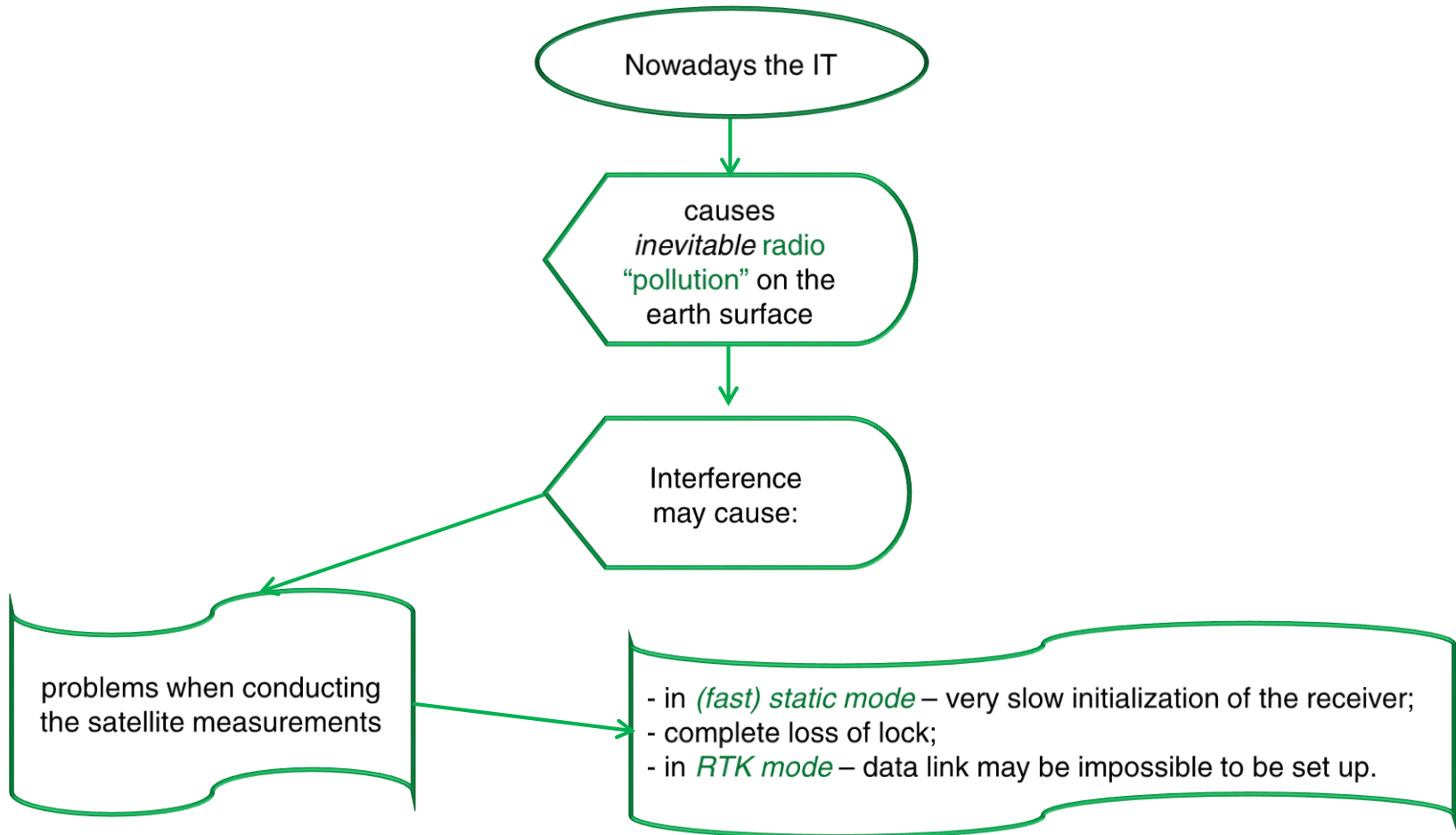
Study of the Behaviour of the Rover and Assessment of the Overall Quality of the Results from RTK Measurements, Conducted in open-Field - Influenced by Active Disturber

Dr. M. Sc. Gintcho Kostov, Bulgaria
“GEO ZEMIA” Ltd.



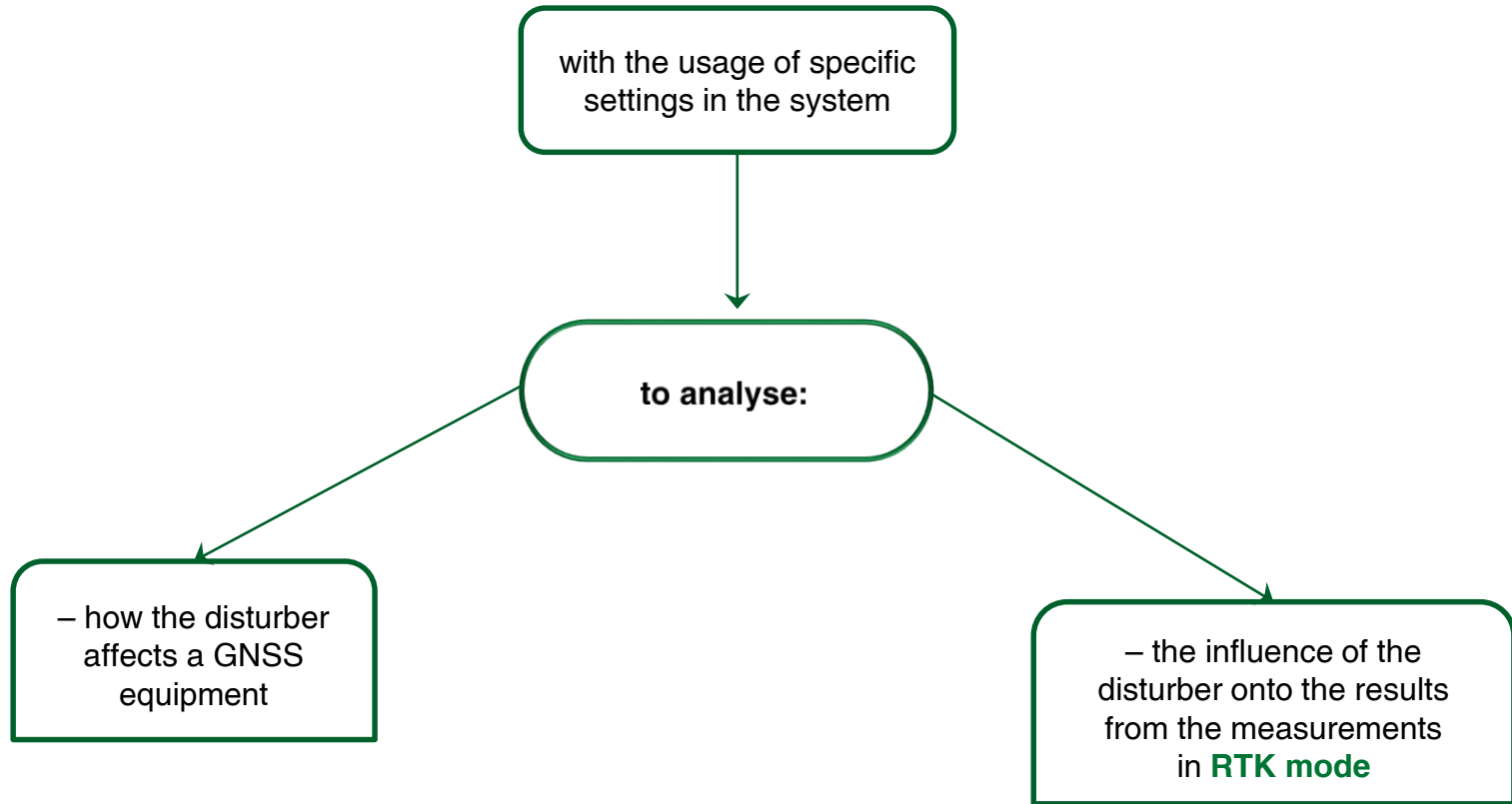
Study of the Behaviour of the Rover and Assessment of the Overall Quality of the Results from RTK Measurements, Conducted in open-Field - Influenced by Active Disturber

1. Introduction



Study of the Behaviour of the Rover and Assessment of the Overall Quality of the Results from RTK Measurements, Conducted in open-Field - Influenced by Active Disturber

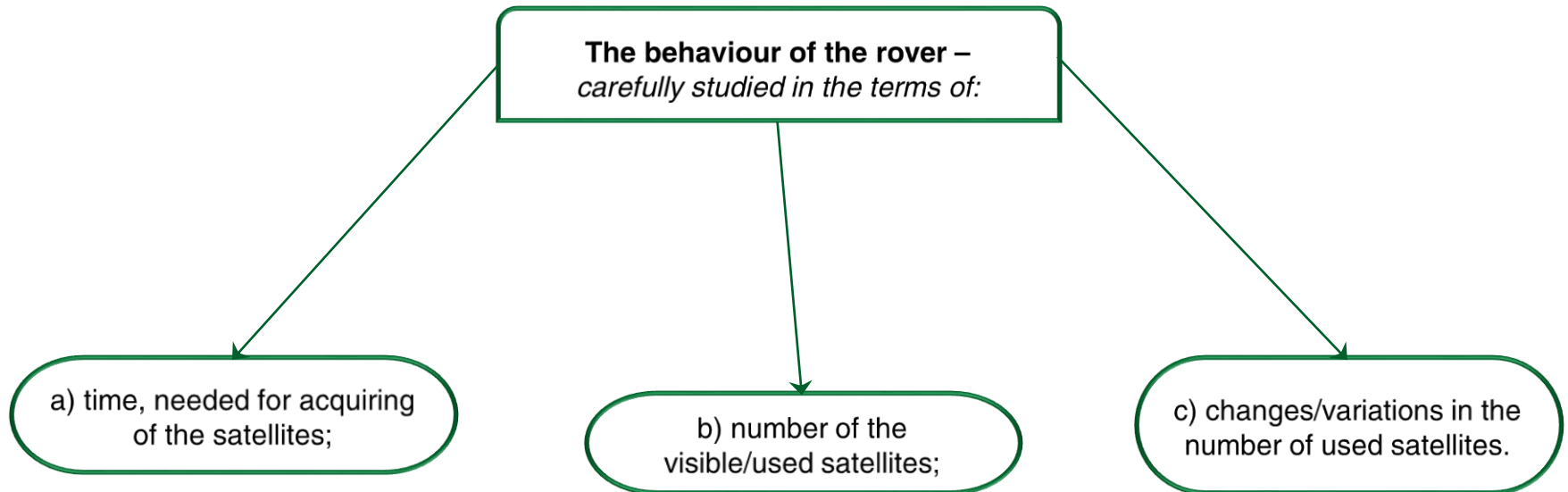
2. Aims of the study



Study of the Behaviour of the Rover and Assessment of the Overall Quality of the Results from RTK Measurements, Conducted in open-Field - Influenced by Active Disturber

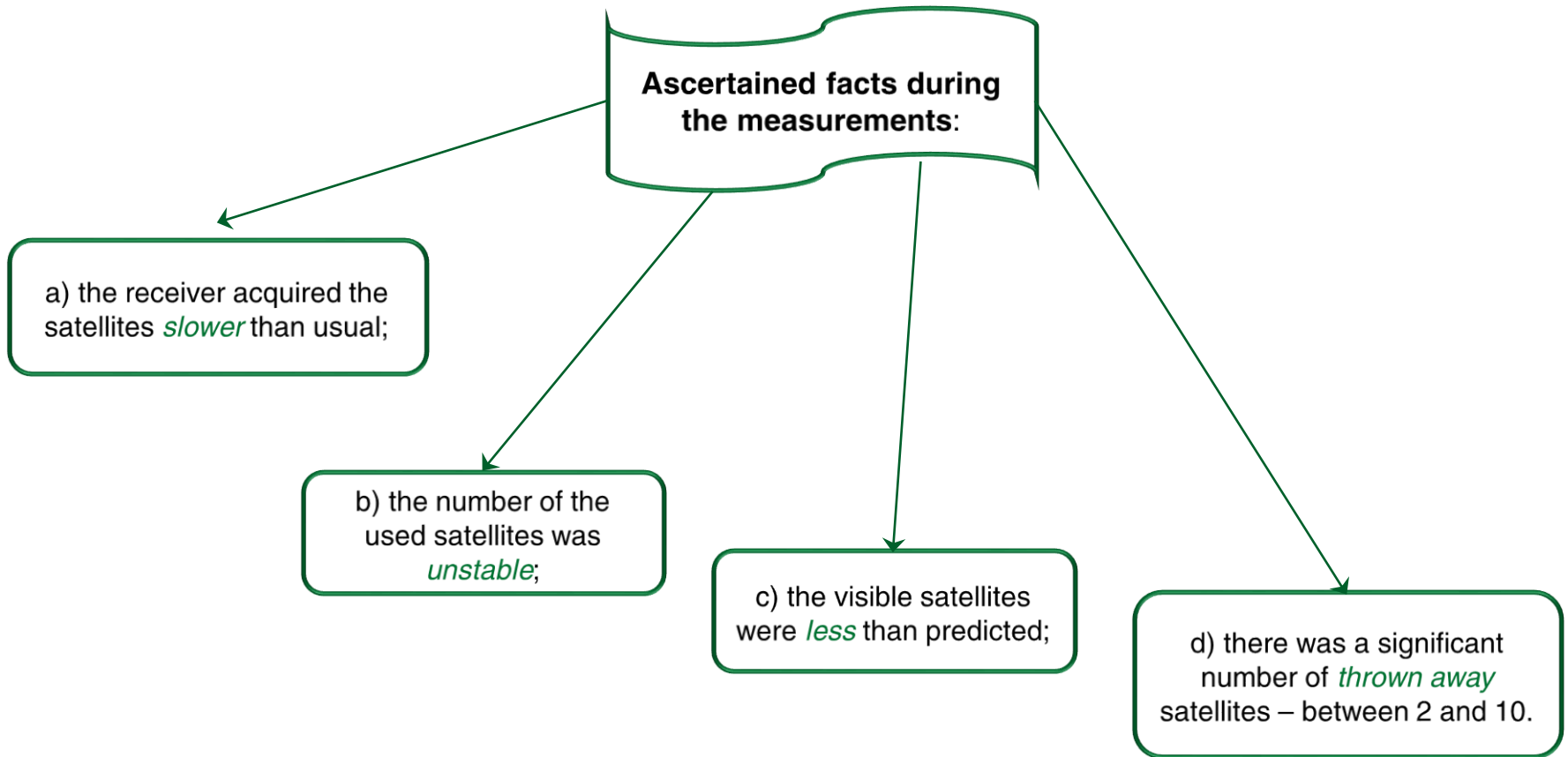
3. Conducted Geodetic Measurements. Study and Specifics of the Behaviour of the Rover

- the reference GNSS station - set up in close proximity to the area under study;
- RTK measurements were conducted inside the disturbed region;
- the lengths of the measured spatial chords were less than 1 km.



Study of the Behaviour of the Rover and Assessment of the Overall Quality of the Results from RTK Measurements, Conducted in open-Field - Influenced by Active Disturber

3. Conducted Geodetic Measurements. Study and Specifics of the Behaviour of the Rover



Study of the Behaviour of the Rover and Assessment of the Overall Quality of the Results from RTK Measurements, Conducted in open-Field - Influenced by Active Disturber

4. Used Criteria for Assessment of the Overall Quality of the Measured points

In this study the following quality criteria were applied:

1. Diagonal elements of the co-variance matrix: Q_{11} , Q_{22} and Q_{33} ;
2. Position quality - M_p ;
3. Height quality - M_h ;
4. Position and height quality - M_{3D} ;



Study of the Behaviour of the Rover and Assessment of the Overall Quality of the Results from RTK Measurements, Conducted in open-Field - Influenced by Active Disturber

5. Results and Analysis from the Measurements in RTK mode



point N	Q11	Q22	Q33	Mp [mm]	Mh [mm]	M3D [mm]	rating
335	0.00001915	0.00001231	0.00009714	6	11	12	0.63
336	0.00001916	0.00001281	0.00010978	6	11	12	0.63
350	0.00001914	0.00001280	0.00010994	5	10	11	0.63
351	0.00001933	0.00001282	0.00011988	5	10	11	0.64
352	0.00001583	0.00001265	0.00010010	5	10	11	0.64
353	0.00001903	0.00001269	0.00010491	6	11	12	0.63
354	0.00002263	0.00002574	0.00029561	7	17	18	0.47
355	0.00001560	0.00001254	0.00009616	5	10	11	0.64
370	0.00001918	0.00001320	0.00010867	5	10	11	0.63
371	0.00001535	0.00001268	0.00010175	5	10	12	0.64

significant difference in the quality

Table 1. Values of the criteria and results for the overall quality assessment

Study of the Behaviour of the Rover and Assessment of the Overall Quality of the Results from RTK Measurements, Conducted in open-Field - Influenced by Active Disturber

5. Results and Analysis from the Measurements in RTK mode

point N	Q11	Q22	Q33	Mp	Mh	M3D	rating
385	0.00001155	0.00001037	0.00009547	6	12	13	0.66
390	0.00001558	0.00001339	0.00020323	6	16	17	0.55
391	0.00001143	0.00001036	0.00009719	4	9	10	0.69
394	0.00001443	0.00001110	0.00012543	6	13	15	0.63
395	0.00001176	0.00001111	0.00012155	5	13	14	0.68
396	0.00001133	0.00001036	0.00010028	4	9	10	0.70
397	0.00001439	0.00001105	0.00011995	4	9	10	0.65
398	0.00001137	0.00001119	0.00011799	5	11	12	0.69
399	0.00000432	0.00000408	0.00004336	10	22	24	0.56
400	0.00001135	0.00001070	0.00010613	5	11	12	0.69
401	0.00001174	0.00001180	0.00014581	5	13	14	0.68
402	0.00001173	0.00001129	0.00013052	5	12	13	0.68
403	0.00001196	0.00001178	0.00015797	5	12	13	0.68
404	0.00001195	0.00001119	0.00013835	6	16	17	0.55
405	0.00001197	0.00001170	0.00015670	6	15	16	0.58
406	0.00001185	0.00001119	0.00013371	6	15	16	0.58

Table 1. Values of the criteria and results for the overall quality assessment - continued

Study of the Behaviour of the Rover and Assessment of the Overall Quality of the Results from RTK Measurements, Conducted in open-Field - Influenced by Active Disturber

5. Results and Analysis from the Measurements in RTK mode

point N	Q11	Q22	Q33	Mp	Mh	M3D	rating
419	0.00001679	0.00001275	0.00012999	8	16	18	0.45
420	0.00001245	0.00001099	0.00011075	6	13	14	0.65
421	0.00001246	0.00001099	0.00011050	6	12	14	0.66
422	0.00001254	0.00001099	0.00010936	5	11	12	0.67
425	0.00001308	0.00001164	0.00012041	8	17	18	0.47
426	0.00001312	0.00001165	0.00011957	7	15	16	0.54
434	0.00001316	0.00001102	0.00009676	5	10	11	0.67
435	0.00001331	0.00001104	0.00009961	5	9	10	0.67
436	0.00001378	0.00001130	0.00010815	5	10	11	0.66
437	0.00001363	0.00001107	0.00010058	6	13	14	0.64
438	0.00001415	0.00001240	0.00010750	6	12	13	0.64
439	0.00001417	0.00001241	0.00010731	6	12	14	0.64
440	0.00001381	0.00001126	0.00010326	6	13	14	0.64
441	0.00001383	0.00001126	0.00010304	6	13	14	0.64
442	0.00001386	0.00001127	0.00010265	7	14	15	0.56
443	0.00001392	0.00001129	0.00010199	6	13	14	0.64

variations in the quality

low quality

equal quality, high rating

Table 1. Values of the criteria and results for the overall quality assessment - last

Study of the Behaviour of the Rover and Assessment of the Overall Quality of the Results from RTK Measurements, Conducted in open-Field - Influenced by Active Disturber

6. Analysis of the Results

According to the calculated results, it could be summarized:

1. variations in the accuracy were ascertained;
2. a degradation of the accuracy *up to 24 mm in the open field* was observed;
3. M3D quality criterion was not sufficient for complete control of the accuracy – for points NN 397 and 398. More criteria should be considered and used.

It must be noted that several years ago in the region under study GNSS measurements could not be conducted due to the strong influence of the active disturber.



Study of the Behaviour of the Rover and Assessment of the Overall Quality of the Results from RTK Measurements, Conducted in open-Field - Influenced by Active Disturber

7. Conclusions

Based on:

- continuous improvement of the system;
- considering the accuracy results,

Geodetic measurements conducted with GNSS equipment nowadays are characterised *with better overall quality and reliability* in comparison with the passed last years.

Taking in mind the quality assessment, the current status of the system and GNSS modernizations it could be concluded:

- Currently enough operational satellites exist, which can be used for geodetic determinations and be delivered good quality results in a region with operating active disturber.
- The future efforts for GNSS improvements are highly encouraged in order to be obtained: better reliability in the determinations and higher overall quality of the results within places with operating active disturber.



Study of the Behaviour of the Rover and Assessment of the Overall Quality of the Results from RTK Measurements, Conducted in open-Field - Influenced by Active Disturber

REFERENCES:

Kostov, G. Assessing of the Overall Quality of GNSS Determinations, Using Specific Values of Parameters. Third International Conference on Cartography and GIS. June, 15-20, Nessebar, Bulgaria, 2010.

Minchev, M., Iv. Zdravcev, Iv. Georgiev, Foundations of the application of GPS in geodesy, Sofia UACEG, 2005 (in Bulgarian).

Ministry of Regional Development and Public Works. Issued DV issue 79/11.10.2011. Instruction N RD-02-20-25/20.09.2011 for determination of geodetic points, using GNSS. In effect from 11.10.2011. (in Bulgarian).

Tiwari R., Soumi Bhattacharyaa, P.K. Purohitb, and A.K. Gwala. Effect of TEC Variation on GPS Precise Point at Low Latitude. The Open Atmospheric Science Journal, 2009.

Tiwari S., Amit Jain, Shivalika Sarkar, Sudhir Jain and A K Gwal. Ionospheric irregularities at Antarctic using GPS measurements. J. Earth Syst. Sci. 121, No. 2, Indian Academy of Sciences, April 2012.

Wellenhof, B., Herbert Lichtenegger, James Collins, GPS Theory and practice, Springer-Verlag/Wien, Austria, 2002. (in Bulgarian).

Study of the Behaviour of the Rover and Assessment of the Overall Quality of the Results from RTK Measurements, Conducted in open-Field - Influenced by Active Disturber

WEB:

<http://en.wikipedia.org/wiki/GLONASS>

http://en.wikipedia.org/wiki/GPS_modernization

http://waas.stanford.edu/~www/papers/gps/PDF/IWG/sbas_iono_scintillations_white_paper.pdf

http://www.ion.org/search/view_abstract.cfm?jp=p&idno=1292

Study of the Behaviour of the Rover and Assessment of the Overall Quality of the Results from RTK Measurements, Conducted in open-Field - Influenced by Active Disturber



Thank you for your attention!